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As know

$$\frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} = -\text{grad} \frac{1}{|\vec{r} - \vec{r}'|}$$

Put this in (A)

$$\vec{A}(x, y, z) = \frac{-\mu_0}{4\pi} \int_V \vec{M}(x', y', z') \times \text{grad} \frac{1}{|\vec{r} - \vec{r}'|} dv' \rightarrow (B)$$

By using vector notation or vector identity

$$\therefore \text{curl } UV = U \text{curl } V + \underbrace{\nabla U \times V}_{\text{grad}}$$

$$\text{let } \vec{M} = V \quad ; \quad \frac{1}{|\vec{r} - \vec{r}'|} = U$$

$$\text{curl}' \left(\frac{\vec{M}}{|\vec{r} - \vec{r}'|} \right) = \frac{1}{|\vec{r} - \vec{r}'|} \text{curl}' \vec{M} + \text{grad} \frac{1}{|\vec{r} - \vec{r}'|} \times \vec{M}$$

Put this value in (B)

$$\vec{A}(x, y, z) = -\frac{\mu_0}{4\pi} \int_{V_0} \text{curl}' \left(\frac{\vec{M}}{|\vec{r} - \vec{r}'|} \right) dv'$$

$$\vec{A}(x, y, z) = -\frac{\mu_0}{4\pi} \int_{V_0} \left[\frac{1}{|\vec{r} - \vec{r}'|} \text{curl}' \vec{M} + \text{grad} \frac{1}{|\vec{r} - \vec{r}'|} \times \vec{M} \right] dv'$$

$$\vec{A}(x, y, z) = \frac{\mu_0}{4\pi} \int_{V_0} \frac{\text{curl}' \vec{M}}{|\vec{r} - \vec{r}'|} dv' - \frac{\mu_0}{4\pi} \int_{V_0} \left(\frac{\text{grad}' \frac{1}{|\vec{r} - \vec{r}'|} \times \vec{M}}{|\vec{r} - \vec{r}'|} \right) dv' \rightarrow (C)$$

Now By using Stoke's Theorem
 $\int \text{curl } \vec{F} \cdot d\vec{v} = \int_S \hat{n} \times \vec{F} \cdot d\vec{a}$

The second term of $\epsilon_V (c)$ becomes
 $\vec{A}(x,y,z) = \frac{\mu_0}{4\pi} \int_{V_0} \frac{\text{curl } \vec{M}}{|\vec{r} - \vec{r}'|} - \frac{\mu_0}{4\pi} \int_S \frac{\hat{n} \times \vec{M}}{|\vec{r} - \vec{r}'|} d\vec{a}'$

Now By inter changing
 $\hat{n} \times \vec{M} = -\vec{M} \times \hat{n}$

$$\vec{A}(x,y,z) = \frac{\mu_0}{4\pi} \int_{V_0} \frac{\text{curl } \vec{M}}{|\vec{r} - \vec{r}'|} + \frac{\mu_0}{4\pi} \int_S \frac{\vec{M} \times \hat{n}}{|\vec{r} - \vec{r}'|} d\vec{a}' \rightarrow (D)$$

$\text{curl } \vec{M}$ is the current density \vec{J}_m due to magnetization. where S_0 is the surface of V_0 . ~~\vec{J}_m is current density over the surface~~

$$\vec{J}_m = \text{curl } \vec{M} \rightarrow (i)$$

$$\vec{j}_m = \vec{M} \times \hat{n} \rightarrow (ii)$$

put this in $\epsilon_V (D)$ so ϵ_V becomes

$$\vec{A}(\vec{r}) = \vec{A}(x,y,z) = \frac{\mu_0}{4\pi} \int_{V_0} \frac{\vec{J}_m}{|\vec{r} - \vec{r}'|} d\vec{v}' + \frac{\mu_0}{4\pi} \int_S \frac{\vec{j}_m}{|\vec{r} - \vec{r}'|} d\vec{a}' \rightarrow (1)$$

where

\vec{J}_m is the magnetization current per unit length flowing in the surface. \vec{j}_m is the magnetization current density.

The vector potential produced by a distribution of atomic currents inside matter has the

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(5)

(2)

same form as that produced by a distribution of true transport currents. Eq. (1) is the proper expression for the surface current density. Abrupt change in \vec{M} occurs due to discontinuity in surface current density which is consistent with

$$\vec{J}_m = \text{curl } \vec{M}$$

\vec{J}_m must be introduced whenever \vec{M} changes abruptly, as it might at the interface between two mediums but if the region of discontinuity in \vec{M} is imagined to be spread out over the distance $\Delta \xi$, then it can be shown that \vec{J}_m is contained in the term $\vec{J}_m \Delta \xi$.

This equation presents some practical difficulties when it comes to the computing \vec{B} from a specified distribution of magnetization.

Gradient of a scalar field is easier to compute than the curl of a vector field.

Again we take

$$\vec{B}(\vec{r}) = \text{curl } \vec{A} = \mu_0 \int_V \frac{\text{curl } \vec{M} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dv'$$

→ (2)

Again using vector notation As,
$$\text{curl}(U \times V) = U \text{div} V - V \text{div} U + (V \cdot \nabla) U - (U \cdot \nabla) V$$

In our case

$$U = \vec{M} \qquad V = \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3}$$

So,

$$\begin{aligned} \text{curl} \left[\vec{M} \times \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right] &= \vec{M} \text{div} \left(\frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) - \left(\frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \right) \text{div} \vec{M} \\ &\quad + \left(\frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \cdot \nabla \right) \vec{M} - \left(\vec{M} \cdot \nabla \right) \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \end{aligned}$$

Since $\text{div} \vec{M}(x', y', z') = 0$, These fore second and third term become zero. The Remaining ϵ_V when put in $\epsilon_V(2)$ is

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \left[\int_{V_0} \frac{\vec{M} \text{div} \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} dv'}{|\vec{r} - \vec{r}'|^3} - \int_{V_0} \frac{(\vec{M} \cdot \nabla) \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3}}{|\vec{r} - \vec{r}'|^3} dv' \right]$$

$$\Rightarrow \vec{B}(\vec{r}) = \vec{B}_1(\vec{r}) + \vec{B}_p(\vec{r})$$

Now

$$\vec{B}_1(\vec{r}) = \frac{\mu_0}{4\pi} \int_{V_p} \frac{\vec{M} \text{div} \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} dv'}{|\vec{r} - \vec{r}'|^3}$$

Changing volume integral into

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surface Integral

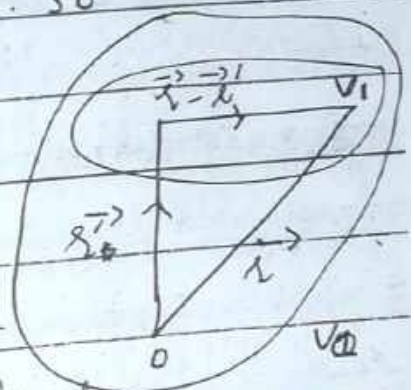
$$\vec{B}_1(x) = \frac{\mu_0}{4\pi} \int_S \vec{M} \frac{(\vec{r} - \vec{r}') \cdot \hat{n} da}{|\vec{r} - \vec{r}'|^3}$$

$$\vec{B}_1(x) = \frac{\mu_0}{4\pi} \vec{M} \int_S \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} \cdot \hat{n} da$$

It is a solid angle. So

$$|\vec{B}_1(x)| = \frac{\mu_0 \vec{M} \times 4\pi}{4\pi}$$

$$\boxed{\vec{B}_1(x) = \mu_0 \vec{M}}$$



In above we consider first \vec{B}_1 integral. It is convenient to divide the volume of the magnet, V_0 into two regions: (1) a small spherical region V_1 surrounding the point (x, y, z) and (2) for remaining volume $V_0 - V_1$. Since the divergence term in the integral vanishes everywhere except at the point $\vec{r} = \vec{r}'$. The integral over $V_0 - V_1$ is zero.

Now we consider \vec{B}_2 integral. Then the integral may be transformed by means of a second identity. i.e.

$$\vec{B}_2(x) = -\frac{\mu_0}{4\pi} \int_{V'} (\vec{M} \cdot \vec{\nabla}') \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|} dv$$

Now Apply vector notation.

$$\nabla \left[\frac{\vec{M} \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \right] = \vec{M} \cdot \nabla \frac{1}{|\vec{r} - \vec{r}'|^3} + M \text{curl} \frac{1}{|\vec{r} - \vec{r}'|^3}$$

here $\text{curl} \frac{1}{|\vec{r} - \vec{r}'|^3} = -\text{curl grad} \frac{1}{|\vec{r} - \vec{r}'|^3}$

So

$$\vec{B}_{II}(\vec{r}) = -\frac{\mu_0}{4\pi} \int_{V'} \nabla \left(\frac{\vec{M} \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} \right) dv'$$

$$\vec{B}_{II}(\vec{r}) = -\frac{\mu_0}{4\pi} \nabla \int_{V'} \frac{\vec{M} \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dv'$$

$$\vec{B}_{II}(\vec{r}) = -\frac{\mu_0}{4\pi} \nabla \cdot \int_{V'} \frac{\vec{M} \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dv'$$

$$\vec{B}_{II}(\vec{r}) = -\mu_0 \nabla U^*(\vec{r})$$

The quantity $U^*(\vec{r})$ is the scalar field we shall call it the magnetic scalar potential due to magnetic material.

$$U^*(\vec{r}) = \frac{1}{4\pi} \int_{V'} \frac{\vec{M} \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dv'$$

So, $\vec{B}(\vec{r}) = \vec{B}_I(\vec{r}) + \vec{B}_{II}(\vec{r})$

$$\vec{B}(\vec{r}) = \mu_0 \vec{M} - \mu_0 \nabla U^*(\vec{r})$$

The first term is the local magnetic field while second term is grad of scalar potential.

Thus the Magnetic Induction due to a magnetized distribution of matter may be expressed as the sum of two terms in the gradient of the scalar field and a term proportional to the local magnetization.

At an external point i.e. in vacuume \vec{M} is zero. $\vec{M} \cdot \vec{I}$ is then just the gradient of the scalar field which is the integral of the distant dipole field.

Magnetic Scalar Potential And Magnetic

Pole Density:-

As magnetic scalar potential is written as

$$U^*(r) = \frac{1}{4\pi} \int_{V_0} \frac{\vec{M}(r') \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dv'$$

It is similar form to that for the electric static potential arising from polarized dielectric material. Now we apply the vector identity

$$U^*(r) = \frac{1}{4\pi} \int_{V_0} \vec{M}(r') \cdot \text{grad} \frac{1}{|\vec{r} - \vec{r}'|} dv'$$

we ignore (-) sign. Now we take dot product of

$$\frac{\vec{M} \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} = \vec{M} \cdot \text{grad} \frac{1}{|\vec{r} - \vec{r}'|} = \text{div} \frac{\vec{M}}{|\vec{r} - \vec{r}'|} - \frac{1}{|\vec{r} - \vec{r}'|} \text{div} \vec{M}$$

So by putting we have

$$U^*(\vec{r}) = \frac{1}{4\pi} \left[\int_{V_0} \frac{\text{div} \vec{M}}{|\vec{r} - \vec{r}'|} dv' - \frac{1}{|\vec{r} - \vec{r}'|} \text{div} \vec{M} dv' \right]$$

$$U^*(\vec{r}) = \frac{1}{4\pi} \int_{V_0} \frac{\vec{M} \cdot \text{div} \vec{M}}{|\vec{r} - \vec{r}'|} dv' - \frac{1}{4\pi} \int_{V_0} \frac{1}{|\vec{r} - \vec{r}'|} \text{div} \vec{M} dv'$$

Taking 1st integral as a surface integral

$$U^*(\vec{r}) = \frac{1}{4\pi} \int_S \frac{\vec{M} \cdot \hat{n}}{|\vec{r} - \vec{r}'|} d\vec{r}' - \frac{1}{4\pi} \int_{V_0} \frac{1}{|\vec{r} - \vec{r}'|} \text{div} \vec{M} dv'$$

1st integral shows surface charge density represented by σ . Where S_0 is the surface of the region V_0 . we include \vec{M} to show magnetic field. Also the 2nd integral equal to volume charge density. For this we defined two scalar quantities

$$\rho_m(\vec{r}') = -\text{div} \vec{M}(\vec{r}')$$

Known as magnetic pole density.

And

$$\sigma_m(\vec{r}') = \vec{M} \cdot \hat{n}$$

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the surface density of magnetic pole strength. If there is uniform magnetized bar then the 2nd integral we vanish

$$U^*(x) = \frac{1}{4\pi} \int_{S_0} \frac{\sigma_m(x')}{|\vec{r} - \vec{r}'|} da' + \frac{1}{4\pi} \int_{V_0} \frac{\rho_m(x')}{|\vec{r} - \vec{r}'|} dv'$$

because

$$\rho_m = 0$$

So

$$U^*(x) = \frac{1}{4\pi} \int_{S_0} \frac{\sigma_m(x')}{|\vec{r} - \vec{r}'|} da'$$

Normal component of magnetized material is left. This statement relates to divergence Theorem

$$\int_S \vec{m} \cdot \hat{n} da + \int_{V_0} (-\text{div } \vec{M}) dv' = 0$$

The total pole strength of every magnet is zero. i.e

$$\nabla \cdot \vec{B} = 0$$

Now we apply divergence theorem to convert ~~volume~~ surface integral to volume

integral. Hence $\vec{B}(x, y, z)$ is obtained as -4π times the gradient w.r.t the unprimed coordinates.

$$\vec{B} = -\mu_0 \nabla U^*(\vec{r}) + \mu_0 \vec{M}(\vec{r})$$

$$\vec{B} = -\frac{\mu_0}{4\pi} \nabla \int_{S_0} \frac{\delta m(\vec{r}')}{|\vec{r} - \vec{r}'|} da' - \frac{\mu_0}{4\pi} \nabla \int_{V_0} \frac{\rho_m(\vec{r}')}{|\vec{r} - \vec{r}'|} dv' + \mu_0 \vec{M}(\vec{r})$$

This eq shows M.I at any far point.

$$\vec{B} = +\frac{\mu_0}{4\pi} \int_{S_0} \frac{\delta m(\vec{r}') (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} da' + \frac{\mu_0}{4\pi} \int_{V_0} \frac{\rho_m(\vec{r}') (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dv' + \mu_0 \vec{M}(\vec{r})$$

This eq represents the contribution from the magnetized material in V_0 to magnetic induction at (x, y, z) .

Sources Of the Magnetic Field:-

⇒ (1)

Magnetic Intensity:-

It is important to know that under certain conditions the same piece of matter produces magnetic field both because of magnetization and also it is carrying a current of charge carriers. The best magnetic materials are Fe, Co, Ni etc. They carry current

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because of free electrons.

one of our best magnetic material iron may carry a current due to free electrons but fixed iron ions in the crystal contains atomic current, which can be oriented to produce a strong magnetization.

The General Expression for Magnetic field

is

$$\vec{B}(\vec{r}) = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}(\vec{r}') (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dv' - \mu_0 \nabla U^*(\vec{r}) + \mu_0 \vec{M}(\vec{r}) \rightarrow (1)$$

where

$$U^*(\vec{r}) = \frac{1}{4\pi} \int_V \frac{\rho_m}{|\vec{r} - \vec{r}'|} dv' + \frac{1}{4\pi} \int_S \frac{\sigma_m da'}{|\vec{r} - \vec{r}'|}$$

The volume V extend, over all current carrying region and over all matter, the surface S includes all surfaces and interfaces between different media.

The current density \vec{J} includes all currents of the charge transport whereas the effect of atomic currents is found in the magnetization vector \vec{M} .

Eq (1) may be solved for \vec{B} if \vec{M} and

\vec{r} are specified at all points. $\vec{M}(\vec{x}, \vec{y}, \vec{z})$ depends on $\vec{B}(\vec{x}, \vec{y}, \vec{z})$ so that even if the functional form of $\vec{M}(\vec{B})$ is known if the provides at best an integral ϵ_p for \vec{B} we add contribution because of current density as current is flowing through atoms.

As, $\vec{B} = \mu_0 \vec{H}$
 $\Rightarrow \vec{H} = \frac{\vec{B}}{\mu_0}$

The magnetic material also has magnetization. The magnetic Intensity \vec{H} defined by $\vec{H} = \frac{\vec{B}}{\mu_0} - \vec{M}$

Putting value of \vec{B} in above.
 $\vec{H} = \frac{\mu_0}{4\pi} \int_V \frac{\vec{J}_x(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dv' - \nabla U^*(r) + \vec{M}(r) - M$

$\vec{H} = \frac{1}{4\pi} \int_V \frac{\vec{J}_x(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dv' - \nabla U^*(r) + \vec{M}(r) - M$

It appears that we have gained nothing by this work because \vec{H} still depends on \vec{r} through ρ_m & \vec{O}_m . A Magnetic materia

which produces magnetization by itself and a non-magnetic material, which induces magnetization by near by object has same result. But now we can show how \vec{H} related to the current density \vec{J} through a differential Equation.

The Field Equation:-

The basic Equations describing the magnetic effects of conventional currents were expressed in differential form is

$$\text{div } \vec{B} = 0$$

$$\text{curl } \vec{B} = \mu_0 \vec{J}$$

we should now like to see how these Equations are modified when the magnetic field \vec{B} includes a contribution from magnetized material. The divergence Equation came about because \vec{B} could be written as the curl of the vector function \vec{A} . But this result is not limited to magnetic fields produced by conventional currents. The field produced by magnetized matter is also derivable from a vector potential.

Thus \vec{B} may always be written as $\text{curl } \vec{A}$ and the divergence equation follows.

$$\text{div } \vec{B} = 0 \rightarrow (1)$$

The "curl equation" is the differential form of Ampere's circuital law. Due to magnetization the eq becomes.

$$\text{curl } \vec{B} = \mu_0 (\vec{J} + \vec{J}_m)$$

where \vec{J}_m is the current density due to magnetization. As,

$$\text{curl } \vec{B} = \mu_0 \vec{J} = \mu_0 (\vec{J} + \vec{J}_m) \rightarrow (2)$$

$$\vec{J}_m = \text{curl } \vec{M}$$

Put this value in eq (2)

$$\text{curl } \vec{B} = \mu_0 (\vec{J} + \text{curl } \vec{M})$$

$$\text{curl } \vec{B} = \mu_0 \vec{J} + \mu_0 \text{curl } \vec{M} \rightarrow (3)$$

~~$$\text{curl } \vec{B} - \mu_0 \text{curl } \vec{M} = \mu_0 \vec{J}$$~~

~~$$\vec{J} = \text{curl} \left[\frac{\vec{B}}{\mu_0} - \vec{M} \right]$$~~

$$\text{curl } \vec{H} = \vec{J} + \text{curl } \vec{M}$$

As

$$\vec{B} = \mu_0 \vec{H}$$

Due to magnetization

$$\vec{B} = \mu_0 (\vec{H} + \vec{M})$$

$$\vec{B} = \vec{H} + \vec{M}$$

μ_0

$$\vec{H} = \vec{B} - \vec{M}$$

μ_0

So Equation (3) written as

$$\text{curl } \frac{\vec{B}}{\mu_0} - \text{curl } \vec{M} = \vec{J}$$

$$\text{curl} \left[\frac{\vec{B}}{\mu_0} - \vec{M} \right] = \vec{J}$$

$$\text{curl } \vec{H} = \vec{J} \rightarrow (4)$$

Hence the auxiliary Magnetic vector \vec{H} is related to the current density through its curl. Eq (1) and (4) are fundamental magnetic field Equation.

These Equations together with appropriate boundary conditions and an experimental relationship between \vec{B} and \vec{H} are sufficient to solve Magnetic problem.

Magnetic field \vec{H} relates with only current density. Now take the surface integral of Eq (4)

$$\int_S \text{curl } \vec{H} \cdot \hat{n} \, d\Omega = \int_S \vec{J} \cdot \hat{n} \, d\Omega$$

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Now Apply divergence Theorem to convert surface integral in to line integral.

$$\oint_C \vec{H} \cdot d\vec{l} = \int_S \vec{J} \cdot \hat{n} \, d\Omega$$

So,

$$\oint_C \vec{H} \cdot d\vec{l} = \bar{I} \quad \text{current flows on surface!}$$

The line integral of \vec{H} is equal to current.
Now take volume integral of

$$\nabla \cdot \vec{B}$$

For more simplification

$$\int_V \text{div } \vec{B} \, dV = 0$$

The line integral of the tangential component of the magnetic intensity around a closed path C is equal to the entire transport current through the area bounded by the curve C .

By using divergence Theorem.

$$\int_S \vec{B} \cdot \hat{n} \, d\Omega = 0$$

The Magnetic flux through any closed surface is zero.